

Documents

Export Date: 23 Jun 2025

Search:

- 1) Trunov, A., Boiko, V., Dymyrov, Y., Mytrokhin, V., Pozdnyikov, A., Tereshchenko, H.
[The formulation and solution of the problem of constructing optimal trajectory as a means of eliminating socio-legal contradictions in the realization of unmanned robotic systems](#)
(2025) CEUR Workshop Proceedings, 3970, pp. 118-130.
- 1) <https://www.scopus.com/inward/record.uri?eid=2-s2.0-105007703310&partnerID=40&md5=4c41993cfa7521cf11ac3b1d4d1859>
Document Type: Conference Paper
Publication Stage: Final
Source: Scopus