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1) Trunov, A.

[Formation of the Method of Description and Control of the Relative Position of the Gripper Phalanges for Anthropomorphic Robot](#)

(2024) CEUR Workshop Proceedings, 3699, pp. 100-110.

1) <https://www.scopus.com/inward/record.uri?eid=2-s2.0-85195958924&partnerID=40&md5=d2baa6648eaf75fccd2d6dc189826f0>

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